9.2.2 Subalgebraic Systems and Product Algebraic Systems Subalgebraic system



Definition 9.10: Let V=<S, f₁, f₂, ..., f_k> be an algebraic system, and let B be a non-empty subset of S. If B is closed under all operations f₁, f₂, ..., f_k, B and S share the same algebraic constants, then <B, f₁, f₂, ..., f_k> is called a *sub-algebraic system* (or simply, a subalgebra) of V. Sometimes, the sub-algebraic system is simply denoted by B.

- Example:
 - < N, + > is a subalgebra of <Z, + >.
 - < N, + ,0 > is also a subalgebra of <Z, +,0> (because N is closed under + and has the same algebraic constants).



9.2.2 Subalgebraic Systems and Product Algebraic Systems Subalgebraic system(e.g.)

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Example:

• < N-{0},+> is a subalgebra of <Z,+>, but not a subalgebra of <Z,+,0>
(because the algebraic constant 0 is not included in N-{0}).

Notes:

- A subalgebra and its original algebra are the same type of algebraic system (they share the same algebraic constants, the same number of operations, and the same operational properties).
- 2 Every algebraic system V always has *at least one subalgebraic system*.





- The *largest subalgebra* is simply *V* itself.
- The *smallest subalgebra* is the set *B* formed by all the algebraic constants in *V*, provided that *B* is closed under all operations in *V*, in this case, *B* constitutes the smallest subalgebra of *V*.
- The *trivial subalgebras* refer to the largest and smallest subalgebras of *V*.
- A proper subalgebra refers to a subalgebra B where B is a proper subset of S, that is, B forms a proper subalgebra of V.
- Example: Let V=<Z,+,0>, and define nZ = { nz | z∈Z}, n is a natural number, then nZ is a subalgebra of V, when n = 1 or 0, nZ is a trivial subalgebra of V, for all other n, nZ is a nontrivial proper subalgebra of V.



9.2.2 Subalgebraic Systems and Product Algebraic Systems • Product algebra



Definition 9.11: Let $V_1 = \langle S_1, \circ \rangle$ and $V_2 = \langle S_2, * \rangle$ be algebraic systems,

- and * are binary operations. The *product algebra* $V_1 \times V_2$ is an algebraic system with a binary operation, defined as $V_1 \times V_2 = \langle S, \bullet \rangle$, where $S = S_1 \times S_2$, and for all $\forall \langle x_1, y_1 \rangle$, $\langle x_2, y_2 \rangle \in S_1 \times S_2$, we have $\langle x_1, y_1 \rangle = \langle x_2, y_2 \rangle = \langle x_1 \circ x_2, y_1 \otimes y_2 \rangle$.
- **Example:** Consider integer addition $V_1 = \langle Z, + \rangle$ and matrix multiplication $V_2 = \langle M_2(R), \cdot \rangle$,

then
$$V_1 \times V_2 = \langle Z \times M_2(\mathbf{R}), \circ \rangle$$
,

- and for all $\forall < z_1, M_1 >, < z_2, M_2 > \in \mathbb{Z} \times M_2(\mathbb{R})$,
- we have $\langle z_1, M_1 \rangle \circ \langle z_2, M_2 \rangle = \langle z_1 + z_2, M_1 \cdot M_2 \rangle$.

For example:
$$<5, \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} > \circ < -2, \begin{pmatrix} 2 & -1 \\ 0 & 1 \end{pmatrix} > = <3, \begin{pmatrix} 2 & -1 \\ 2 & 0 \end{pmatrix} >$$





- Let $V_1 = \langle S_1, \circ \rangle$ and $V_2 = \langle S_2, * \rangle$ be algebraic systems, where \circ and * are binary operations. The product algebra is $V = \langle S_1 \times S_2, \bullet \rangle$.
 - (1) If and * are **commutative**, then the operation is also **commutative**.
 - (2) If and * are **associative**, then the operation is also **associative**.
 - (3) If and * are **idempotent**, then the operation is also **idempotent**.
 - (4) If \circ and * have respective **identity elements** e_1 and e_2 then the operation \bullet also has an *identity elements* $< e_1, e_2 >$.
 - (5) If \circ and * have respective zero elements θ_1 and θ_2 , then the operation

• also has a *zero element* < θ_1 , θ_2 >.

(6) If x has an inverse x^{-1} , with respect to \circ , and y has an inverse y^{-1} with respect to *, then $\langle x, y \rangle$ has an inverse $\langle x^{-1}, y^{-1} \rangle$ with respect to \bullet .



9.2 Algebraic Systems



- 9.2.1 Definition and Examples of Algebraic Systems
- 9.2.2 Subalgebraic Systems and Product Algebraic Systems
- 9.2.3 Homomorphisms and Isomorphisms of Algebraic Systems





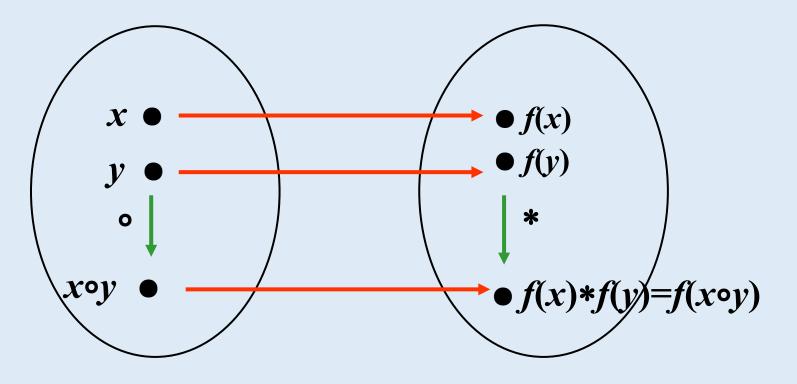
Definition of Homomorphism

- Classification of Homomorphisms
 - Monomorphism, Epimorphism, Isomorphism
 - Endomorphism
- Examples of Homomorphisms
- Properties of Epimorphism





Definition 9.12: Let $V_1 = \langle S_1, \circ \rangle$ and $V_2 = \langle S_2, * \rangle$ be algebraic systems, where \circ and * are binary operations. If there exists a mapping f: $S_1 \rightarrow S_2$, such that $\forall x, y \in S_1$, $f(x \circ y) = f(x) * f(y)$ then f is called a homomorphism from V_1 to V_2 , or simply a homomorphism.





9.2.3 Homomorphisms and Isomorphisms of Algebraic Systems
Examples of homomorphism of algebraic systems (groups)



Example : V=<R*,·>, determine which of the following functions are homomorphisms of V?

(1) f(x) = |x| (2) f(x) = 2x (3) $f(x) = x^2$

(4) f(x)=1/x (5) f(x)=-x (6) f(x)=x+1

Solution: Analyze whether the function satisfies f(x·y)=f(x)·f(y) for all x, y in the nonzero real numbers set R*. (1) f(x·y) = |x·y| = |x| · |y| = f(x) · f(y) homomorphisms (2) f(x·y)=2(x·y) ≠ f(x)·f(y)=(2x)·(2y)=4xy non-homomorphic (3) f(x·y)=(x·y)²=f(x)·f(y)=x²·y² homomorphisms (4) f(x·y)= 1/(x·y)=f(x)·f(y)= 1/x·1/y homomorphisms (5) f(x·y)=-(x·y) ≠ f(x)·f(y)=(-x)·(-y)=xy non-homomorphic (6) f(x·y)=x·y+1≠ f(x)·f(y) (x+1)·(y+1)=xy+x+y+1 non-homomorphic



9.2.3 Homomorphisms and Isomorphisms of Algebraic Systems
 Homomorphisms and Monomorphisms of Algebraic Systems



- Let f be a homomorphism from V₁=<S₁, > to V₂=<S₂, *>, if f is injective (one-to-one), then f is called a monomorphism.
 - Note: f being injective (or a one-to-one mapping) means that for any $x_1, x_2 \in S_1$, if $f(x_1)=f(x_2)$, then $x_1=x_2$.
- Example: Let $V_1 = \langle R^*, \cdot \rangle$, $V_2 = \langle R^*, \cdot \rangle$, and define the mapping $f:R^* \rightarrow R^*$ 为 $f(x)=x^2$. Is f a monomorphism ?
 - We need to verify the homomorphism property and injectivity.
 - Homomorphism: We need to check whether for all $x,y \in \mathbb{R}^*$, the equation $f(x \cdot y) = f(x) \cdot f(y)$ holds. Since $f(x \cdot y) = (x \cdot y)^2 = f(x) \cdot f(y) = x^2 \cdot y^2$, thus $f(x) = x^2$ satisfies the homomorphism property.
 - Injectivity: We need to check whether for all $x_1, x_2 \in R^*$, if $f(x_1)=f(x_2)$, then $x_1=x_2$. For example, if $x_1=-1$, $x_2=1$, we have $x_1^2=x_2^2=1$, but $x_1 \neq x_2$, Therefore, the mapping $f(x)=x^2$ is not injective.
 - Conclusion: $f(x)=x^2$ is a homomorphism, but it is not a monomorphism.



- Let f be a homomorphism from $V_1 = \langle S_1, \circ \rangle$ to $V_2 = \langle S_2, * \rangle$, if f is surjective (onto), then f is called an *epimorphism*. In this case, V_2 is called the **homomorphic image** of V_1 , denoted $V_1 \stackrel{f}{\sim} V_2$.
 - Note: f being surjective (or an onto mapping) means that it is covering, i.e., for every element y in S_2 , there exists some element x in S_1 such that f(x)=y.
- **Example:** Let $V_1 = \langle Z, + \rangle$, $V_2 = \langle Z_3, +_3 \rangle$ (the set of integers modulo 3 with addition modulo 3), and define the mapping $f: Z \to Z_3$ be defined by $f(x) = x \mod 3$. Is f an epimorphism ?



9.2.3 Homomorphisms and Isomorphisms of Algebraic Systems
Surjective homomorphism of algebraic systems(e.g.)



 Homomorphism: We need to check whether for all x,y∈Z, f(x+y)=f(x) +₃ f(y). Since f(x+y)=(x+y)mod 3, f(x) +₃ f(y)=(x mod 3 + y mod 3) mod 3, by the distributive property of modular arithmetic, we have f(x+y)=f(x) +₃ f(y), Therefore f(x)= x mod 3 satisfies the homomorphism property.
 Surjectivity: For each element y in Z₃, does there exist some x in Z₃ such that f(x)=y. Since every element in Z₃ (0, 1, 2) can be obtained by taking modulo 3 of some integer, f is surjective. That is, f is an epimorphism.

- Conclusion: f(x) = x mod 3 is a homomorphism and is indeed an epimorphism.
- Note: Since x₁ and x₂ having the same remainder under f(x) = x mod 3 does not imply that x₁ = x₂, f is not injective, that is, f is not a monomorphism.





Let f be a homomorphism from $V_1 = \langle S_1, \circ \rangle$ to $V_2 = \langle S_2, * \rangle$, if f is bijective, then f is called an *isomorphism* from V_1 to V_2 denoted as $V_1 \cong V_2$.

- Note: *f* being bijective (or a one-to-one and onto mapping) means that *f* is both injective (one-to-one) and surjective (onto). The existence of an isomorphism between two algebraic systems means that their algebraic structures are equivalent.
- Example: Let $V_1 = \langle R, + \rangle$, $V_2 = \langle R, + \rangle$, $f: R \rightarrow R$ be defined by f(x) = 2x. Is the mapping f an isomorphism from V_1 to V_2 ?
 - we need to verify two conditions: the mapping is a homomorphism, and it is bijective.



9.2.3 Homomorphisms and Isomorphisms of Algebraic Systems
Isomorphism of algebraic systems(e.g.)



- Homomorphism: f(x+y)=2(x+y)=2x+2y=f(x)+f(y), which shows that f is a homomorphism.
- Bijectivity :
 - Injectivity: If $f(x_1)=f(x_2)$, then $2x_1=2x_2$, which leads to $x_1=x_2$, showing that f is injective.
 - Surjectivity: For every real number $y \in R$, there exists x=y/2, such that $f(x)=2\cdot y/2=y$ showing that f is surjective.
 - Since *f* is both injective and surjective, it is bijective.
- Conclusion:

f(x)=2x is an *isomorphism* from V1 to V2, and it preserves the properties of the addition operation (closure, commutativity, associativity, identity element, and inverse element).



9.2.3 Homomorphisms and Isomorphisms of Algebraic Systems
Endomorphisms and automorphisms of algebraic systems



- A homomorphism $f:S \rightarrow S$ from an algebraic $V = \langle S, \circ \rangle$ to itself is called an *endomorphism*. That is, for all $x, y \in S$ we have $f(x \circ y) = f(x) \circ f(y)$.
- A zero homomorphism maps every input element to the zero element in the target algebraic structure.
- An *automorphism* refers to a homomorphism *f*:S→S of the algebraic system V=(S, •) that is both injective and surjective, indicating that the system is structurally equivalent to itself.
- A monomorphic endomorphism (or injective endomorphism) is a special type of endomorphism that is also injective.



9.2.3 Homomorphisms and Isomorphisms of Algebraic Systems Endomorphisms and automorphisms of algebraic systems(e.g.



- Example: let $V = \langle Z, + \rangle$, $\forall a \in Z, f_a : Z \rightarrow Z, f_a(x) = ax$. Prove that f_a is an endomorphism of V.
 - Since $\forall x, y \in \mathbb{Z}$, we have: $f_a(x+y) = a(x+y) = ax+ay = f_a(x)+f_a(y)$.
 - When **a** = **0** , **f**₀ is called the zero homomorphism, when **a**=±**1**, **f**_a is called an *automorphism*.
 - For all other values of *a*, *f*_{*a*} is an *injective endomorphism* (monomorphic endomorphism).



9.2.3 Homomorphisms and Isomorphisms of Algebraic Systems
 Homomorphisms and Isomorphisms in Algebraic Systems(e.g.)



- **Example:** Let $V_1 = \langle Q, + \rangle$, $V_2 = \langle Q^*, \cdot \rangle$, where $Q^* = Q_{-}\{0\}$ is the set of nonzero rational numbers. Define $f: Q \rightarrow Q^*$, $f(x) = e^x$. Determine the type of homomorphism that f(x) defines from V_1 to V_2 .
- **Solution:**
 - f is a homomorphism from V_1 to V_2 , because $\forall x, y \in Q$, have $f(x+y)=e^{x+y}=e^x \cdot e^y=f(x) \cdot f(y)$.
 - *f* is a monomorphism because for $\forall x, y \in Q$, If $f(x_1)=f(x_2)=e^{x^2}=e^{x^2}$, which implies $x_1=x_2$, *f* is *injective*.
 - However, for any $y \in Q_*$, e^x cannot reach every nonzero rational number (for example, negative numbers), so $f(x) = e^x$ is not surjective.



9.2.3 Homomorphisms and Isomorphisms of Algebraic Systems
 Homomorphisms and Isomorphisms in Algebraic Systems(e.g.)



- Example: Let $V = \langle Z_n, \oplus \rangle$, $f_p: Z_n \rightarrow Z_n$, $f_p(x) = (xp) \mod n$, p = 0, 1, ..., n-1. Analyze the properties of f_p .
 - (1) Homomorphism: $\forall x, y \in Z_n, f_p(x \oplus y) = ((x \oplus y)p) \mod n = (xp) \mod n$ n ⊕ (yp) mod $n = f_p(x) \oplus f_p(y)$.
 - (2) f_p is an *endomorphism*. Both the input and output of f_p are Z_n , and it satisfies the homomorphism property.
 - ③ If p and n are coprime, then f_p is injective (Monomorphism). For example, when n=6 and p=3(which are not coprime), we have f_p(1)=(1·3) mod 6 =3, but x₁=1 ≠ x₂ =3, so it is not injective.



9.2.3 Homomorphisms and Isomorphisms of Algebraic Systems
 Homomorphisms and Isomorphisms in Algebraic Systems(e.g.)



- **Example:** Let $V = \langle Z_n, \oplus \rangle$, $f_p: Z_n \to Z_n$, $f_p(x) = (xp) \mod n$, p = 0, 1, ..., n-1. Analyze the properties of f_p .
 - (4) Surjectivity (*Epimorphism*): If *p* and *n* are coprime, then *f_p* is surjective. For example, with *n*=6 and *p*=3 (not coprime), in Z₆, for y=0, there is *x*=0,2,4, for *y*=3, there is *x*=1,3,5, but for *y*=1,2,4,5, no *x* satisfies *f_p(x)=y*.
 - **(5)** Zero Homomorphism: If p=0, then $f_p(x) = (x \cdot 0) \mod n = 0$, which means it maps all inputs to zero. Therefore, f_p is the zero homomorphism.
 - 6 Automorphism: If *p* and *n* are coprime, f_p satisfies both injectivity and surjectivity (bijectivity), so f_p is an *automorphism*.



9.2.3 Homomorphisms and Isomorphisms of Algebraic Systems Properties of epimorphism between Algebraic Systems



Let V_1 and V_2 be algebraic systems, and let $f: V_1 \rightarrow V_2$, be a surjective (onto) homomorphism. Then:

- (1) If the operation \circ in V_1 is commutative (associative, idempotent), then the corresponding operation \circ' in V_2 is also *commutative* (associative, idempotent).
- (2) If \circ is distributive over * in V_1 , then the corresponding \circ' is distributive over *' in V_2 .
- (3) If \circ and * are absorbent (absorption law holds) in V_1 , then the corresponding \circ' and *' are also *absorbent* in V_2 .
- (4) If \circ in V_1 has an identity element e_1 (or a zero element θ_1), then $f(e_1)$) (or $f(\theta_1)$) is the *identity (or zero) element* for the corresponding operation \circ' in V_2 .
- (5) If the inverse of x under in V_1 is x^{-1} , then the *inverse* of f(x) under the corresponding •' in V_2 is $f(x^{-1})$.